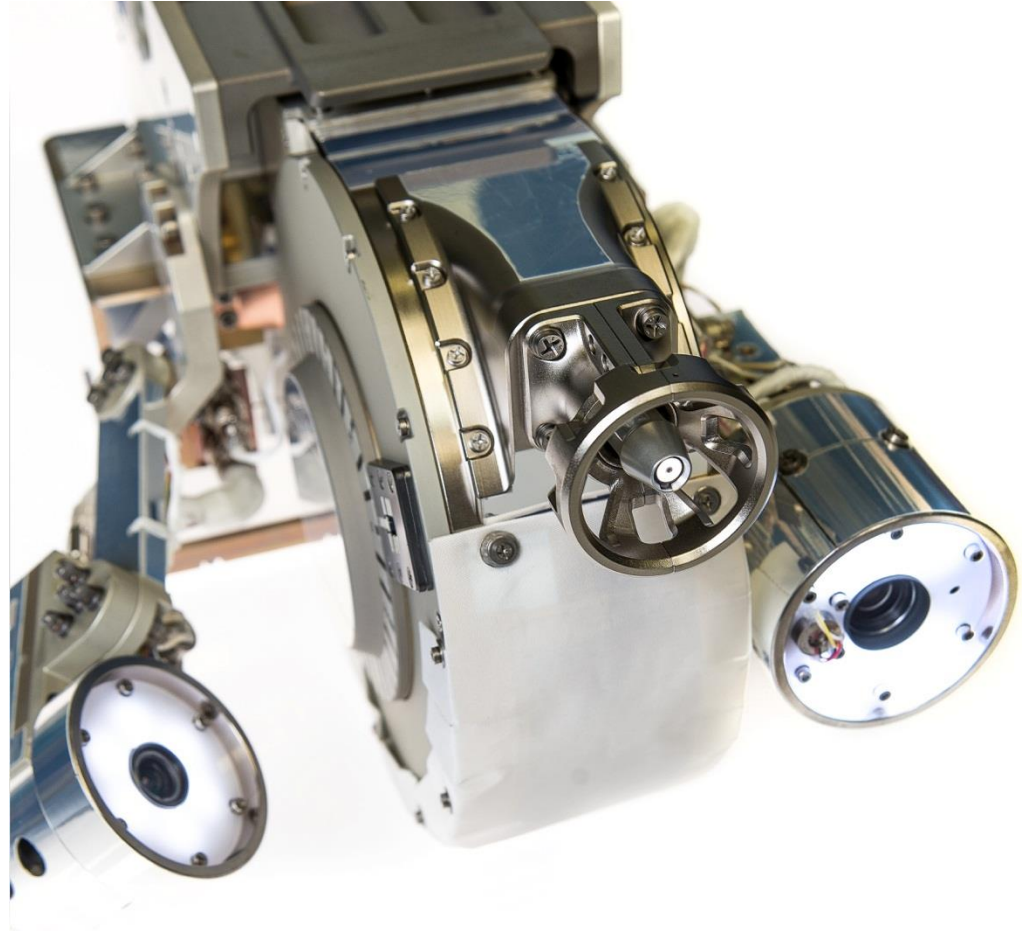


Satellite Servicing Mission – Inspection Needs

Presented to the
NASA In-Space Inspection Workshop
July 15, 2014

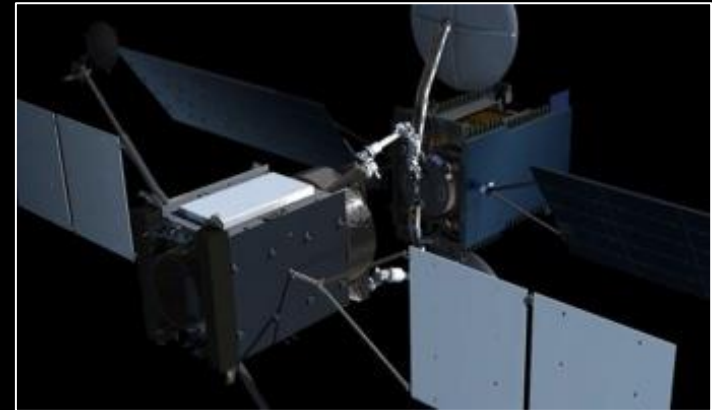


Jill M. McGuire, | Space Robotics Applications Lead
Satellite Servicing Capabilities Office (SSCO)
NASA's Goddard Space Flight Center | Jill.M.McGuire@nasa.gov | <http://ssco.gsfc.nasa.gov>

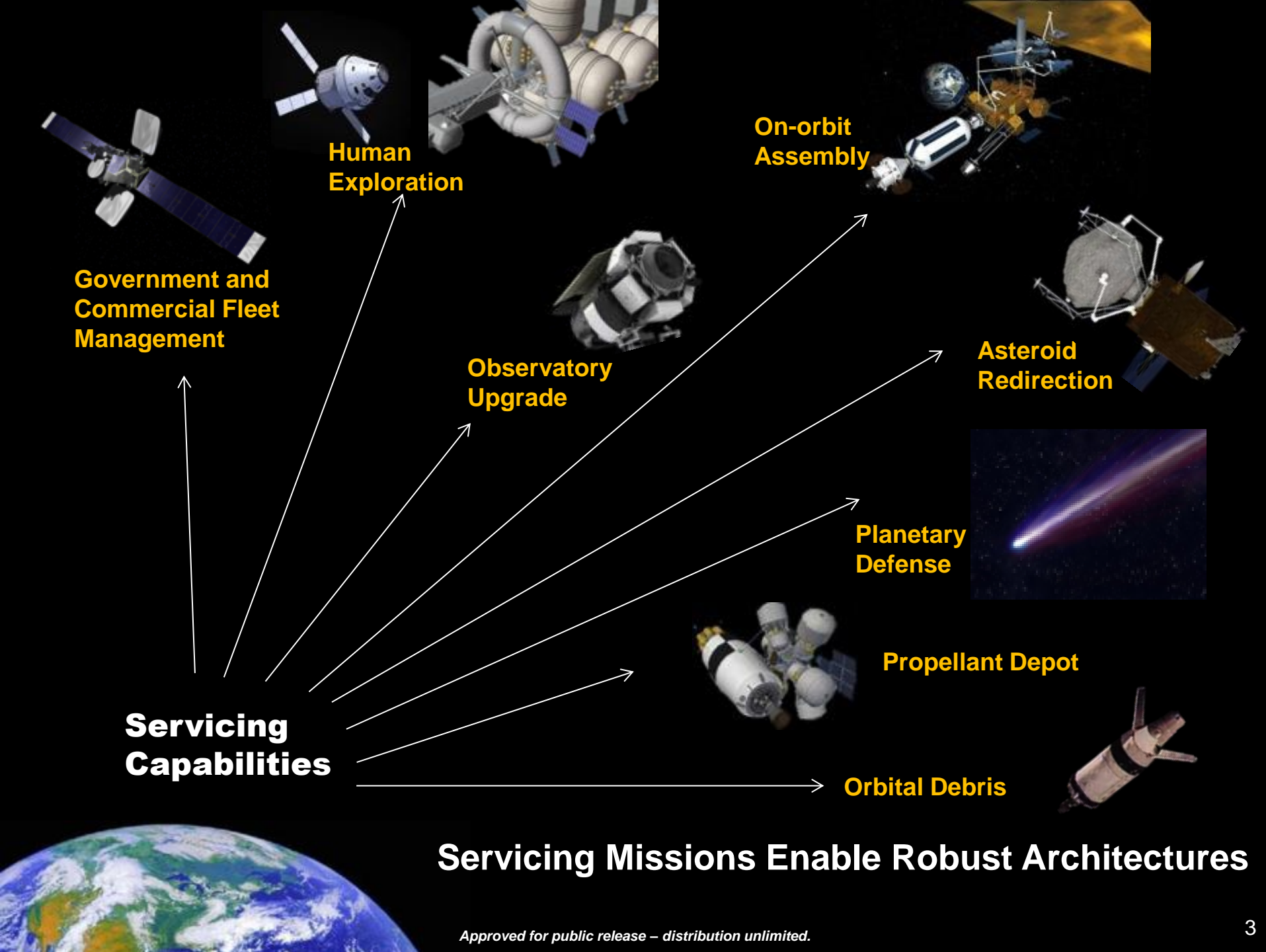
Servicing provides capabilities for
flexible, resilient architectures.



**Anomaly Recovery
Instrument Upgrade
Life Extension**



**In-Orbit Construction
Cryogen Replenishment &
Fueling**

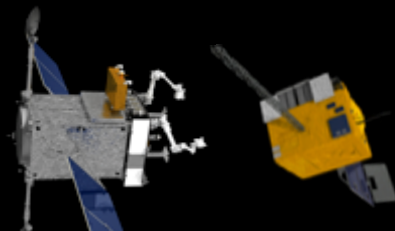


Servicing Missions Enable Robust Architectures

Technologies That Support the Five Servicing R's



Remote Survey | Relocation | Refueling | Repair | Replacement



Autonomous rendezvous & docking sensors & algorithms



Dexterous robotics



High-speed, fault-tolerant computing



Advanced robotic tools



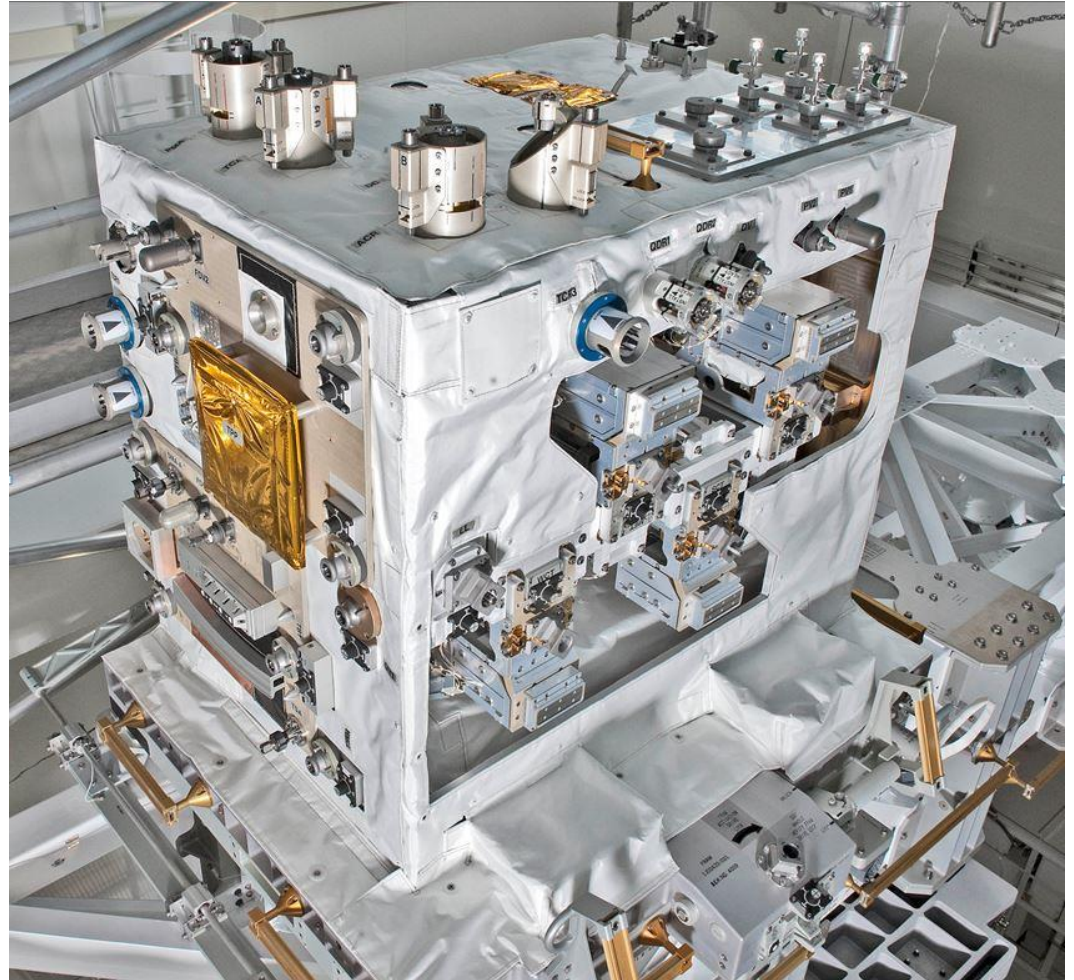
Propellant transfer



Robotic Refueling Mission



RRM was developed to demonstrate the robotic technologies needed to complete the Five “R”s and give NASA the confidence to refuel, repair and maintain satellites in both near and distant orbits.



Advanced Robotic Tools



Multiple tools and adapters developed for NASA's Robotic Refueling Mission demonstration on the International Space Station.



Safety Cap Tool (SCT)



EVR Nozzle Tool (ENT)



Visual Inspection Poseable Invertebrate Robot (VIPIR)

The MFT provides an interface with several adapters.



MLI/Wire Cutter Tool (WCT)



WCT completing cut T-Valve wire



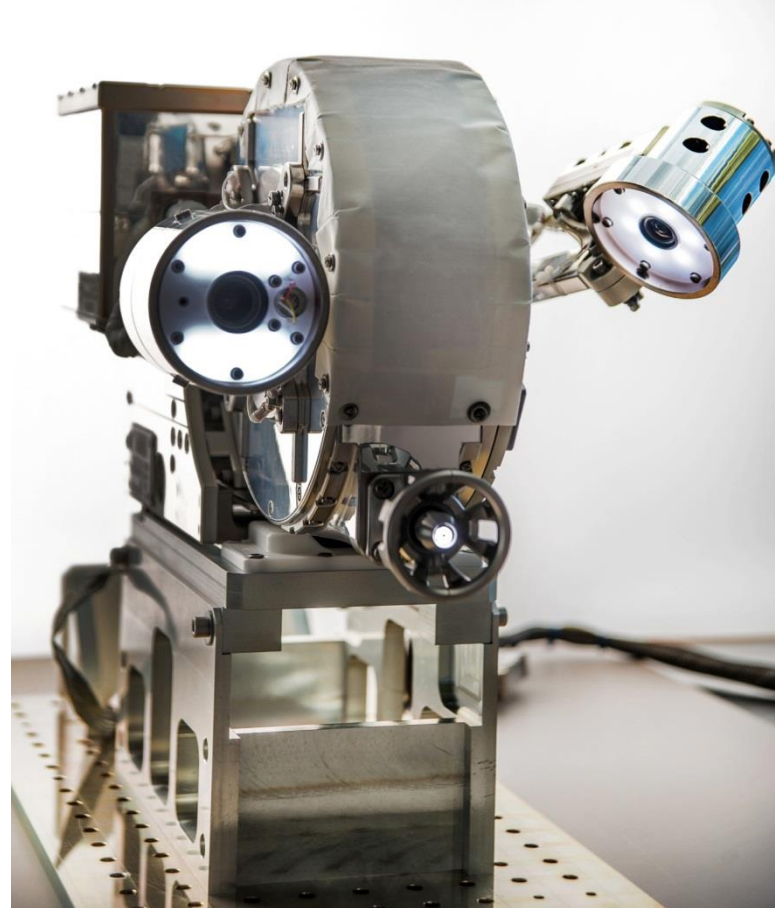
Adapter Suite



Multi-Function Tool

VIPIR is a robotic, teleoperated inspection tool equipped with an articulating, deployable borescope and a second motorized zoom-lens camera.

- Provides close- and midrange inspection capabilities
- Borescope
 - Nearly three feet of deployable tube
 - Final 2.5 inches rotate up to 90 degrees in four opposing directions
 - 1.2 mm color camera at tip
 - Ideal for inspection at 1-2 inches from subject
- Motorized Zoom Lens
 - 24mm optical zoom lens
 - Can resolve worksite details as tiny as 0.02 inch while tool stays 2 feet from spacecraft
- Situational camera
 - Helps control tool during operations



VIPIR Vision System – Design Overview

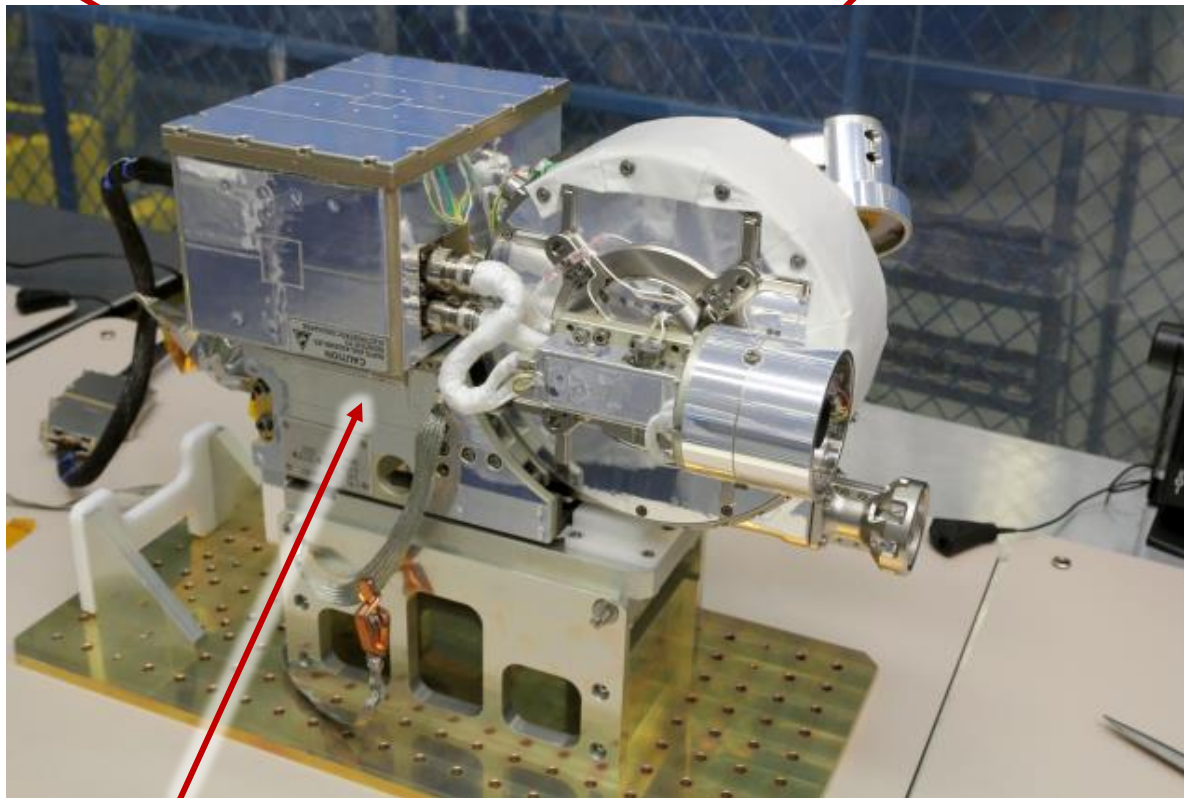


VIPIR Electronics Box (VEB)

Provides VIPIR Motor Controller, Power Conditioning, Camera Selector Electronics, Lighting, and Heater Electronics

VIPIR Tool Assembly

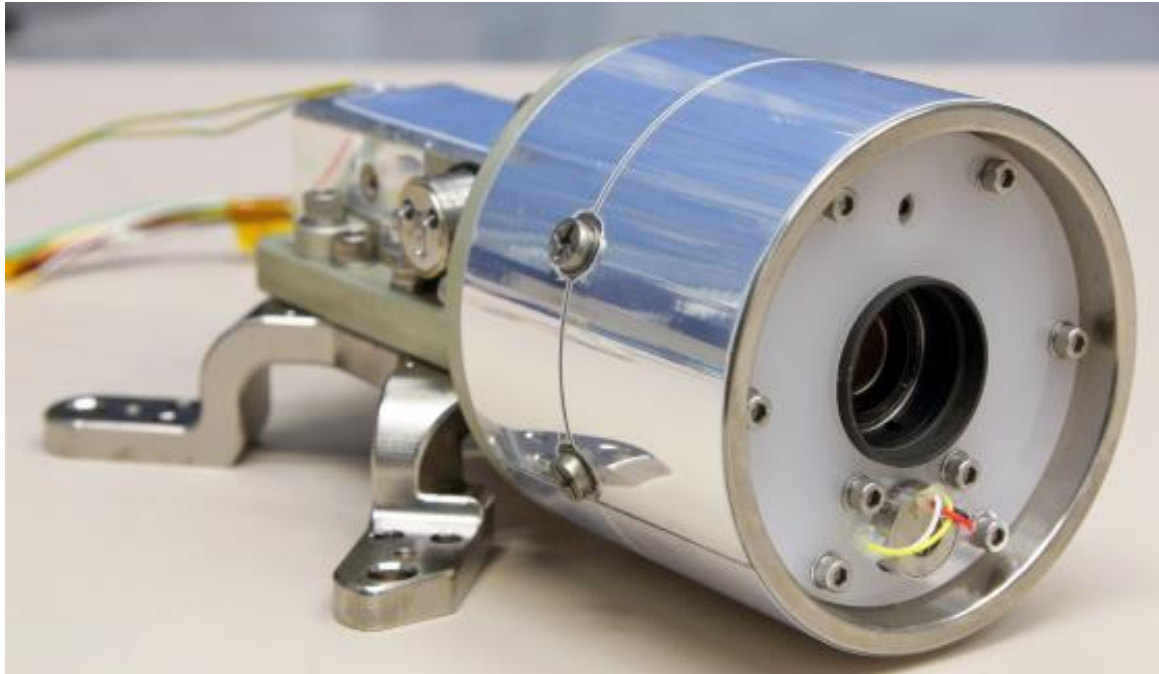
Electro-Mechanical Mechanism provides storage, deployment, and actuation mechanisms for the Video Borescope Assembly (VBA) “Snake Camera”



VIPIR Support Structure (VSS)

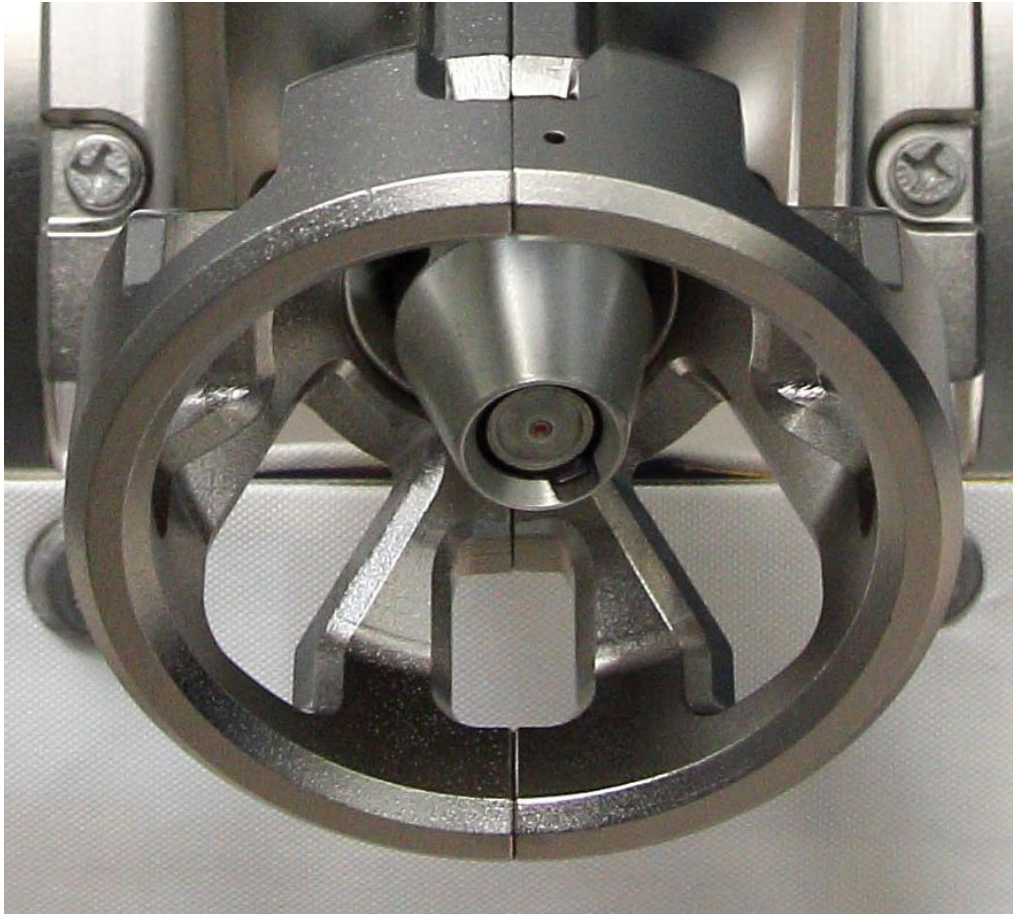
Provides universal RRM stowage interfaces and supporting structure for VIPIR Tool Assembly and VIPIR Vision System

VIPIR - Motorized Zoom Lens (MZL) Camera



Motorized Zoom Lens Camera **Mid-range Inspection Camera** **NTSC, Color, VGA (640 x 480)**

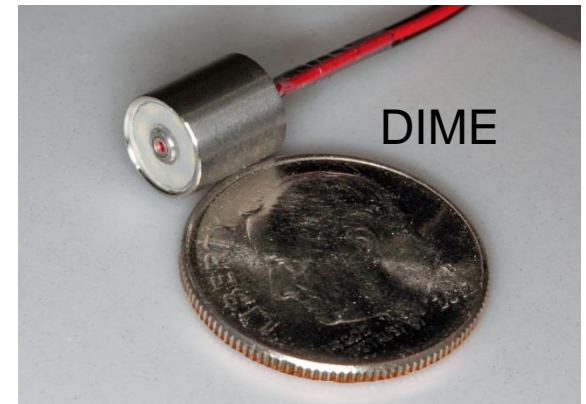
- This camera, with miniature motorized 8-24mm optical zoom and focus capability, will be used for worksite inspection and tool positioning at 8mm focal length
- At 24mm focal length, this camera will serve as an excellent mid-range detailed inspection camera
- FOV (ideal):
 - 44° x 34° @ 8 mm
 - 15° x 12° @ 24 mm
- Pixel Pitch: 8.4 μm (H) x 9.8 μm (V)
- Focus Distance: 50 mm to infinity



Video Borescope Assembly (VBA) Miniaturized Close-range Inspection Camera

NTSC, Color, (224 x 224)

- This camera with lens assembly is only 1.2mm in diameter
- Designed to be deployed into an open orifice, tube, or cavity with minimum 0.90" diameter cross-section
- With integrated miniaturized lighting at the tip, the VBA provides its own lighting in very tight work spaces
- Field of View (FOV): $\sim 100^\circ$
- Pixel Pitch: 2.2 microns square
- Focus Distance (ideal): ~ 6 mm to ~ 50 mm



VIPIR - Fixed Camera & VIPIR's Camera Illumination



VBA

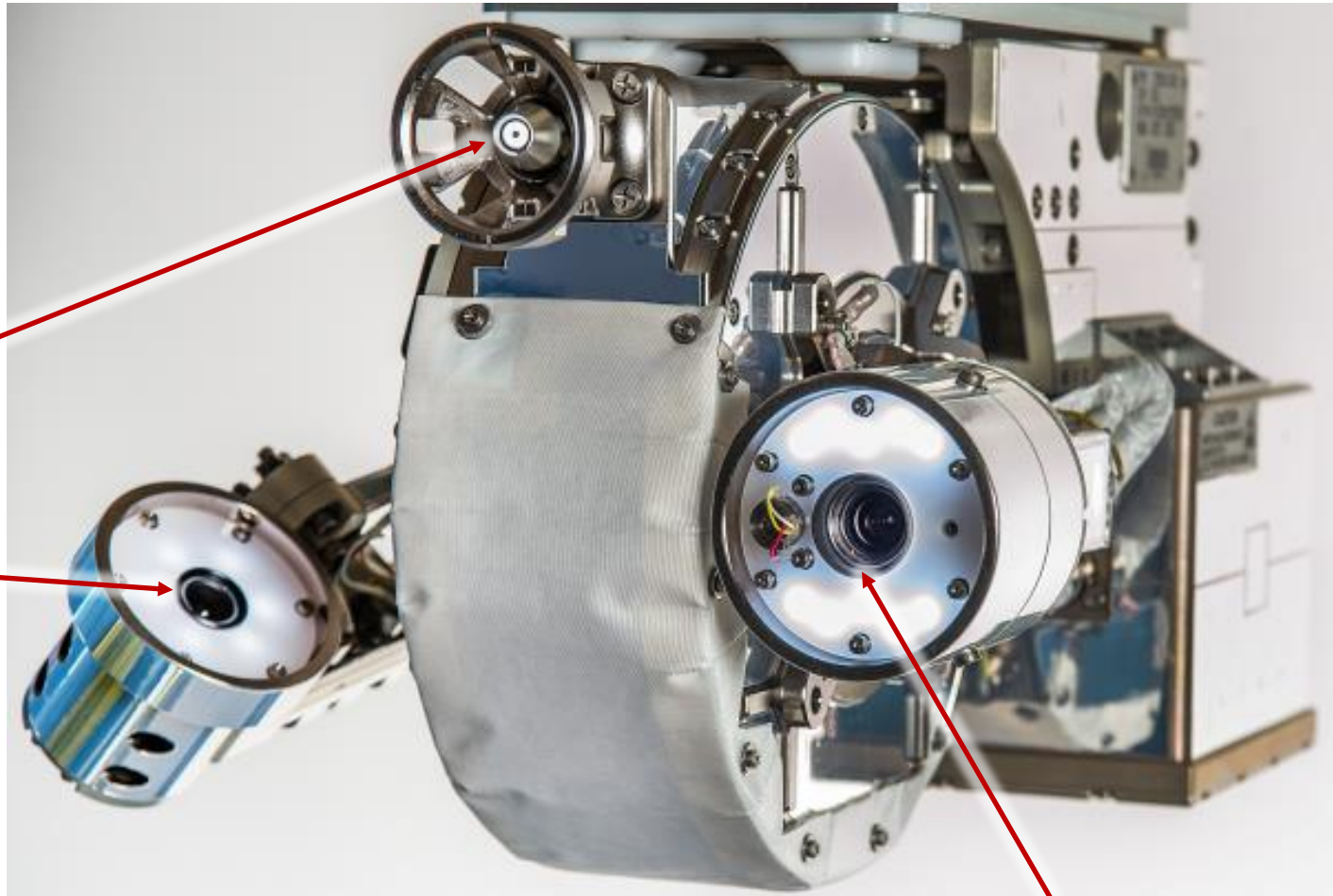
Fixed Camera

Primary Tool Vision
Camera

NTSC, Color, VGA (640 x
480)

This camera, with a fixed
6mm focal length has full
view of Reel Position visual
indicators and will be used
as the primary camera for
tele-operation, tool
positioning, and VBA
deployment

RRM Heritage

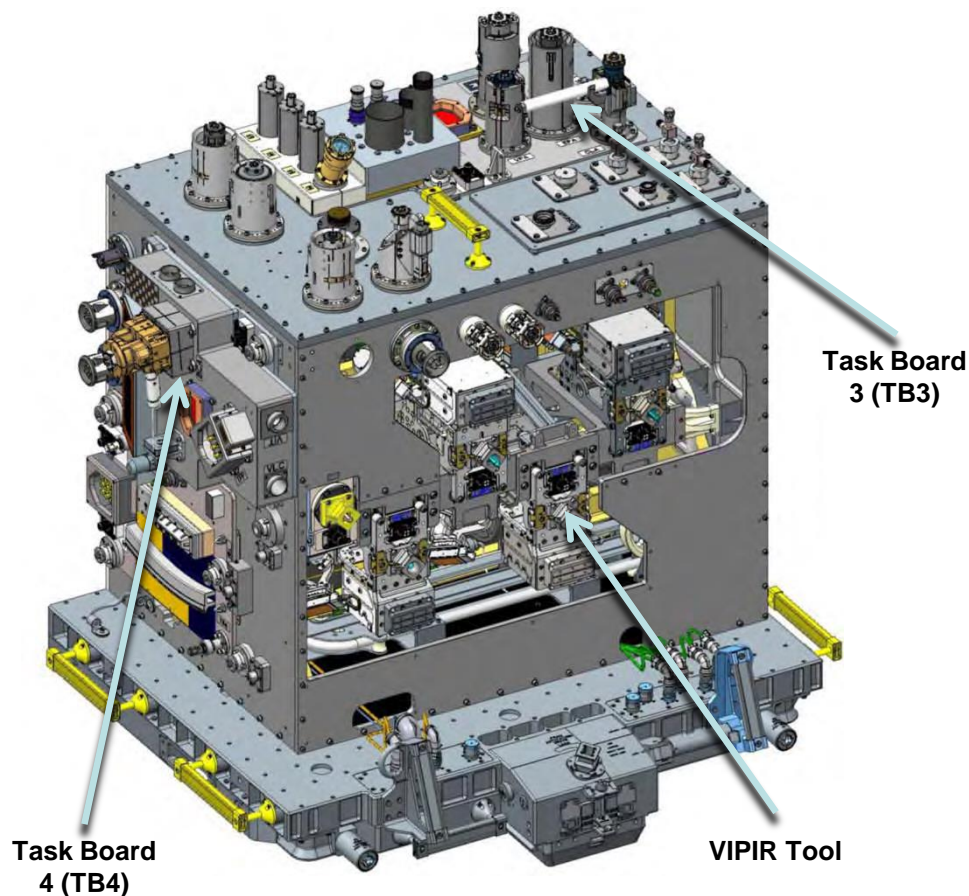


MZL

RRM Phase 2 Configuration



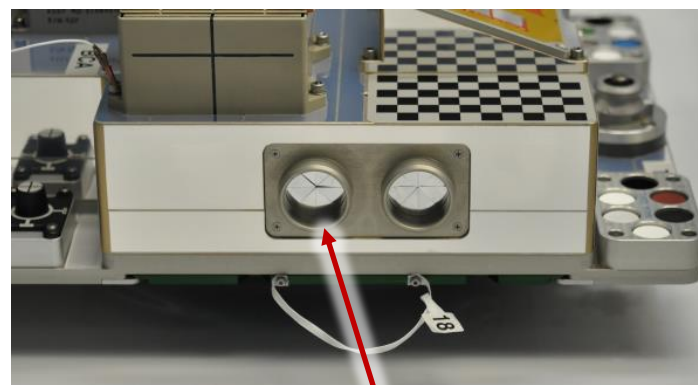
RRM was designed to be modular to allow for augmentation with new tools and task boards to expand the technology knowledge base.



**RRM Phase 2
Configuration**

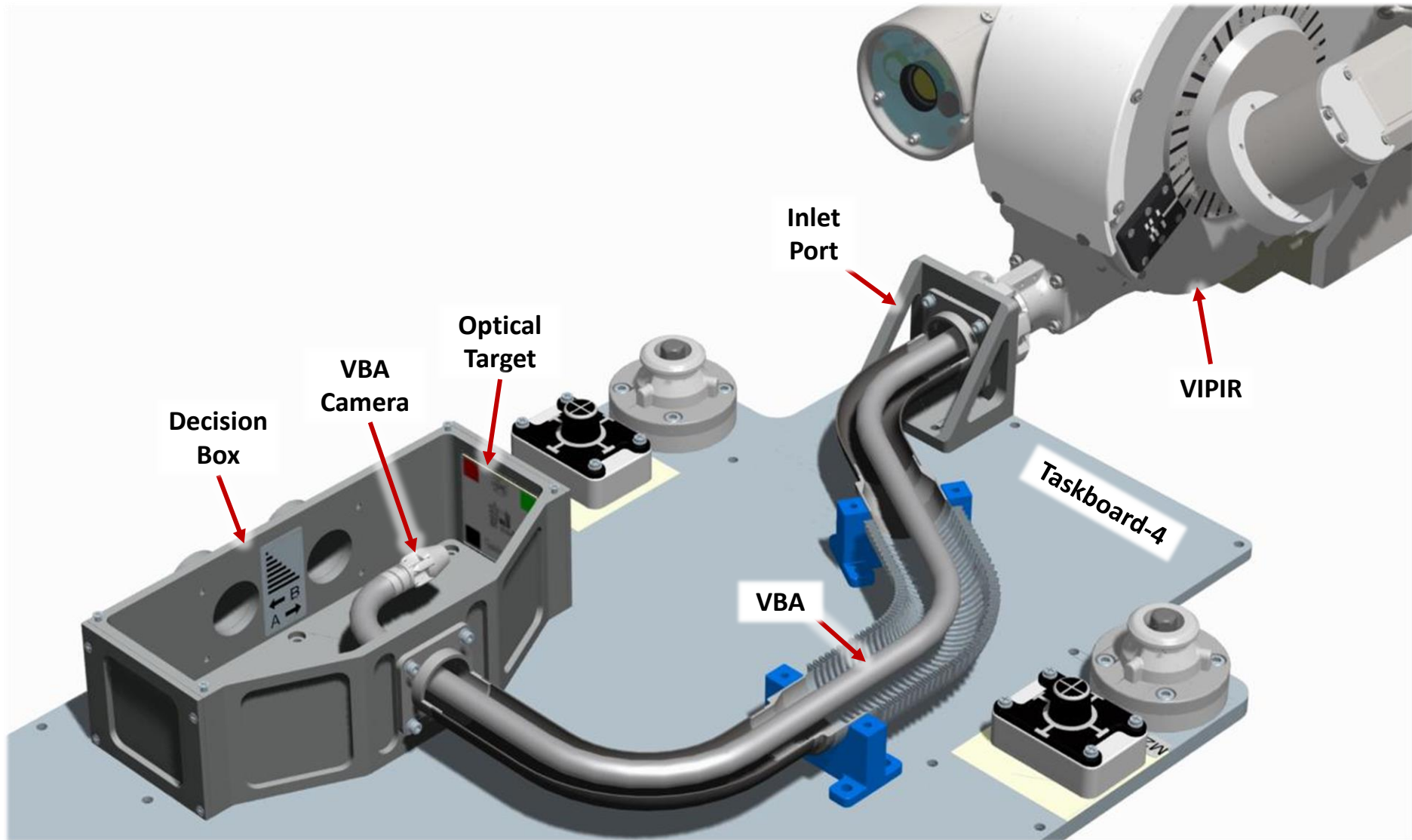


Inspection Tube Entrance Port



Inspection Tube Exit Ports

RRM Task Board 4 - VIPIR Vision System Operation



VIPIR Video Borescope Articulation Video



VIDEO



VISUAL INSPECTION POSEABLE INVERTEBRATE ROBOT (VIPIR)
VIDEO BORESCOPE ARTICULATION
ROBOTIC REFUELING MISSION (RRM) PHASE-2B
NASA GODDARD SATELLITE SERVICING CAPABILITIES OFFICE

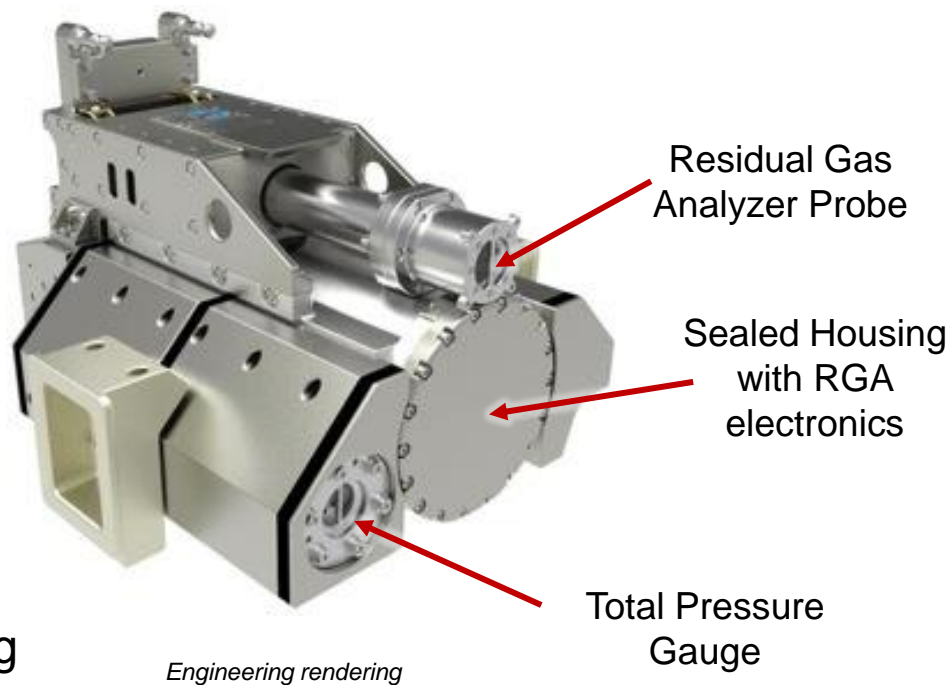


Robotic Residual Gas Analyzer Tool



A space qualified Residual Gas Analyzer instrument that can detect minute traces of impurities in a vacuum environment

- Mass spectrometer (RGA) and pressure gauge sense molecular flux
- Measurements at different locations and orientations provide source location
- Utilizes repackaged commercial sensors to reduce cost; sensors flight-qualified through testing
- Potential uses include environment studies and spacecraft safety, including studies of atomic oxygen and component outgassing, as well as detecting leaks in propulsion and life-support systems





<http://ssco.gsfc.nasa.gov>